

CAN_IO_DOT_MATRIX

Configuration Manual

Description

The device can be configured through any **CANopen** lift configuration tool using the corresponding EDS file:

CAN_IO_DOT_MATRIX.eds. You can download the file here:

<https://semitron.atlassian.net/wiki/spaces/PS/pages/1519648784/CAN+IO+DOT+MATRIX>

Node-ID

The node-ID is an identifier that is unique to every CANopen device connected on the same bus. To change the node-ID, set the desired value on index 0x2000. To apply the change, click on store parameters on your preferred configuration tool and reset the node.

Recommended node-ID values for Floor I/O panels are 21 to 84.

General entries

| Index | Name | Description |
|----------|----------------|---|
| ● 0x6001 | ● Lift number | ● Specifies which lift (1-8) the device is assigned to (for multi-lift applications). |
| ● 0x6002 | ● Floor number | ● Floor number of the device (1–255) |
| ● 0x6003 | ● Door number | ● Specifies which door(s) the device is assigned to (for floors with multiple doors). |



These entries determine the overall behavior of the device. Display and sound indications rely on the general entries to function correctly.



Inputs

| Index | Name | Description | | | | | | | | | | | | | | | |
|----------|--------------------------------|---|----------|---------|-------|---|------|--------|--|----|---------|---|------|---------|--|----|--------|
| ● 0x6100 | ● Call input group | <ul style="list-style-type: none"> 8 inputs can be configured to support several input signal modes. These can be hall calls, car calls, etc. | | | | | | | | | | | | | | | |
| ● 0x6120 | ● Input State Parameters | <ul style="list-style-type: none"> This configuration parameter can be used to enable or disable the corresponding input. <p>Inputs enable status (default: ON)</p> | | | | | | | | | | | | | | | |
| ● 0x6160 | ● Input Calibration Parameters | <ul style="list-style-type: none"> This configuration parameter defines can be used in order to define the button debounce time and the polarity. <p>Button debounce time – default: 20ms The debounce-time refers to the amount of time which is required to trigger an input to transmit the input signal</p> <p>Polarity (invert)</p> <table border="1"> <thead> <tr> <th>Polarity</th><th>Voltage</th><th>Input</th></tr> </thead> <tbody> <tr> <td>0</td><td>+24V</td><td>Enable</td></tr> <tr> <td></td><td>0V</td><td>Disable</td></tr> <tr> <td>1</td><td>+24V</td><td>Disable</td></tr> <tr> <td></td><td>0V</td><td>Enable</td></tr> </tbody> </table> | Polarity | Voltage | Input | 0 | +24V | Enable | | 0V | Disable | 1 | +24V | Disable | | 0V | Enable |
| Polarity | Voltage | Input | | | | | | | | | | | | | | | |
| 0 | +24V | Enable | | | | | | | | | | | | | | | |
| | 0V | Disable | | | | | | | | | | | | | | | |
| 1 | +24V | Disable | | | | | | | | | | | | | | | |
| | 0V | Enable | | | | | | | | | | | | | | | |
| ● 0x2020 | ● GPIO Pull UP/Down | <ul style="list-style-type: none"> Each input can be configured to be enabled to +24V (when user chooses ‘Pull down’) or to 0V (when user chooses ‘Pull up’). -Choose FALSE(0) to configure ‘Pull down’ -Choose TRUE(1) to configure ‘Pull up’ | | | | | | | | | | | | | | | |

Outputs

| Index | Name | Description | | | | | | | | | | | | | | | |
|----------|-----------------------------------|---|----------|---------|-------|---|------|--------|--|----|---------|---|------|---------|--|----|--------|
| ● 0x6200 | ● Call Output group | <ul style="list-style-type: none"> 8 outputs can be configured to support several output signal modes. These can be call acknowledgements, direction indications, arrival indications, etc. | | | | | | | | | | | | | | | |
| ● 0x6210 | ● Special Indication Output group | <ul style="list-style-type: none"> 16 special indications such as "Overload" and "Out of order", can be configured to display a custom message. The display message for each special indication, can be specified on index 0x62b1. | | | | | | | | | | | | | | | |
| ● 0x6220 | ● Output State Parameters | <ul style="list-style-type: none"> This configuration parameter can be used to enable or disable the corresponding output. <p>Outputs enable status (default: ON)</p> | | | | | | | | | | | | | | | |
| ● 0x6260 | ● Output Calibration Parameters | <ul style="list-style-type: none"> This configuration parameter can be used in order to define the polarity. <p>Polarity (invert)</p> <table border="1"> <thead> <tr> <th>Polarity</th><th>Voltage</th><th>Input</th></tr> </thead> <tbody> <tr> <td>0</td><td>+24V</td><td>Enable</td></tr> <tr> <td></td><td>0V</td><td>Disable</td></tr> <tr> <td>1</td><td>+24V</td><td>Disable</td></tr> <tr> <td></td><td>0V</td><td>Enable</td></tr> </tbody> </table> | Polarity | Voltage | Input | 0 | +24V | Enable | | 0V | Disable | 1 | +24V | Disable | | 0V | Enable |
| Polarity | Voltage | Input | | | | | | | | | | | | | | | |
| 0 | +24V | Enable | | | | | | | | | | | | | | | |
| | 0V | Disable | | | | | | | | | | | | | | | |
| 1 | +24V | Disable | | | | | | | | | | | | | | | |
| | 0V | Enable | | | | | | | | | | | | | | | |



Display Options

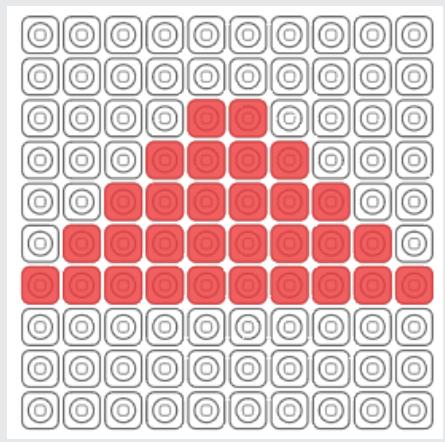
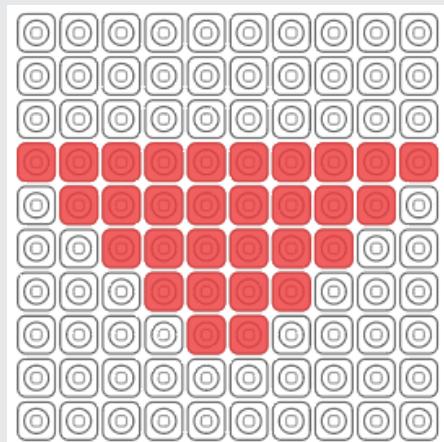
| Index | Name | Description |
|----------|----------------------------|--|
| • 0x62b0 | • Floor name | • Floors display names (up to 32 floors) |
| • 0x62b1 | • Special indications text | • Special indications display message |

0x2005 - Display / Graphic Options

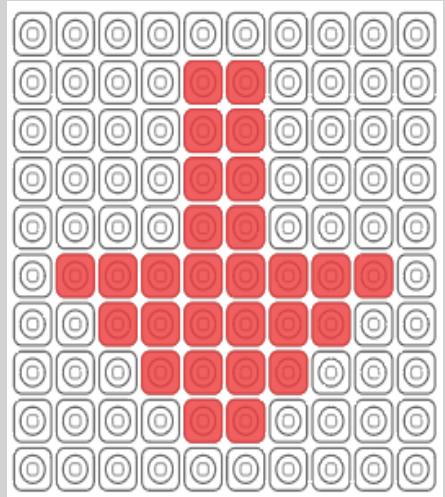
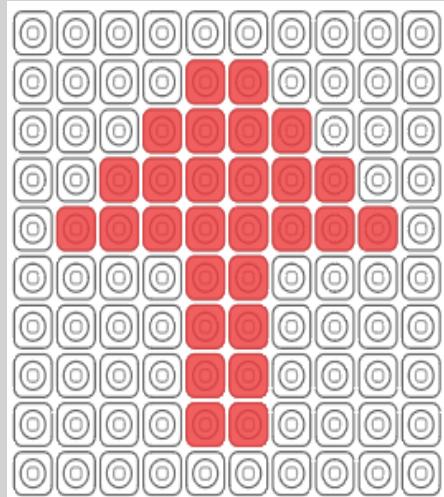
| Sub - Index | Name | Description |
|-------------|----------------------|---|
| 1 | Display Brightness | Display Brightness (1-5) |
| 2 | Display Orientation | <ul style="list-style-type: none"> • Portrait mode (default) • Landscape mode |
| 3 | Arrow Graphic Type | Arrow Graphic selection (1-2 see table below) |
| 4 | Arrow Speed | Moving Arrow speed (1-5) |
| 5 | Text Speed | Moving Text speed (1-5) |
| 6 | Arrow Offscreen Time | Refers to the delay of the arrow reappearance every time it disappears after the completion of its movement. (0-5 which correspond to 0-1.5s) |

△▽ Arrow Graphic selections

1



2



🔊 Sound Options

| 0x2010 - Sound Options | | |
|------------------------|------------------------|--|
| Sub - Index | Name | Description |
| 1 | Arrival Gong | Enable Sound indication on arrival (ON/OFF) |
| 2 | Call Acknowledge Sound | Enable call acknowledge tone (ON/OFF) |

Firmware Updates

Firmware updates are supported to provide the latest features and bug fixes for the device. Click on the "Update firmware" option on your preferred configuration tool and select the update file. The tool will guide you through the process and notify you, once the update is finished.



To apply any changes done to the parameters, click on store parameters on your preferred configuration tool.



CANopen device profile for Lift



Conformed with quality management systems standards

