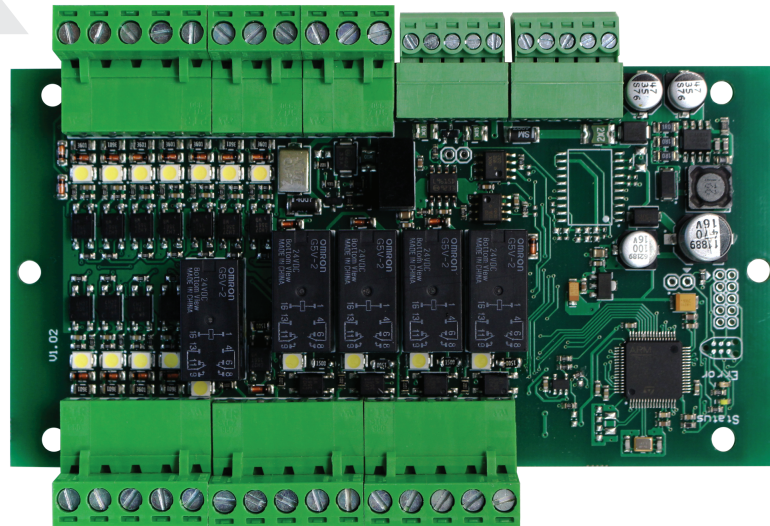


Description

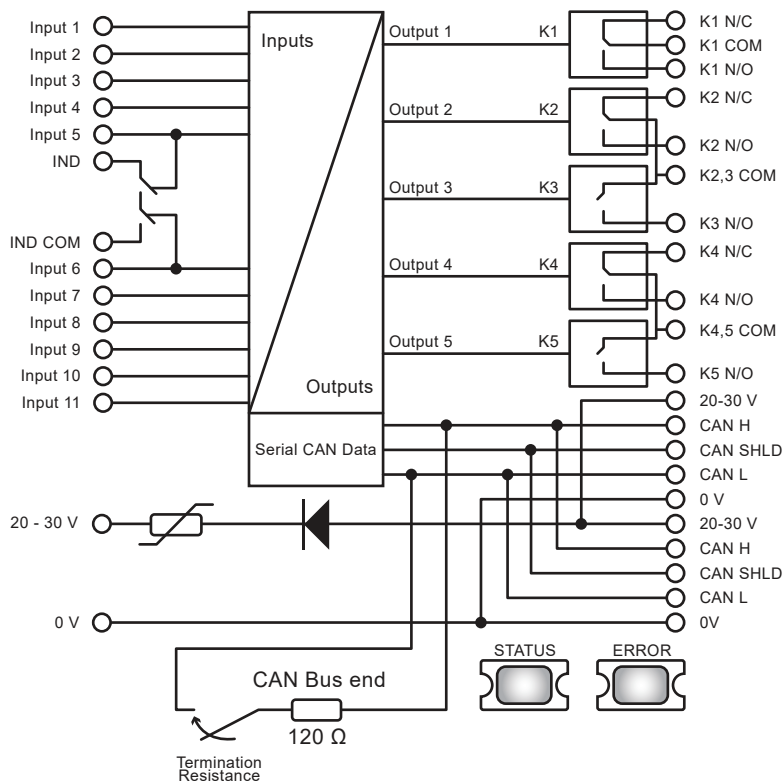
CANopen_REV_LIGHT is a lift car CPU for CANopen-Lift. It is equipped with 5 relay outputs and 11 dedicated inputs, all of which are programmable.

The device can be configured easily through CANopen-Lift configuration tool.

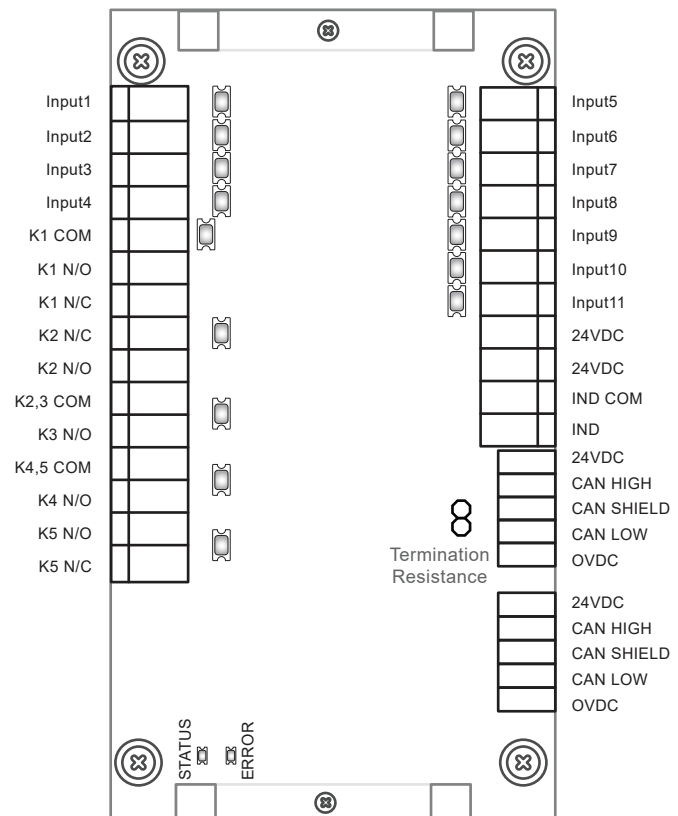
Picture



Block Diagram



Terminals Diagram



Terminals

CAN Bus	<ul style="list-style-type: none"> Relays K1 - K5
<ul style="list-style-type: none"> CAN Bus Interface fully isolated 	<ul style="list-style-type: none"> K1, K2, K5 N/C
<ul style="list-style-type: none"> CAN HIGH 	<ul style="list-style-type: none"> K1 - K5 N/O
<ul style="list-style-type: none"> CAN SHIELD 	<ul style="list-style-type: none"> K2,3 and K4,5 COM
<ul style="list-style-type: none"> CAN LOW 	<ul style="list-style-type: none"> IND
Inputs - Outputs	<ul style="list-style-type: none"> IND COM
<ul style="list-style-type: none"> Input1 - Input11 	Termination Resistance
<ul style="list-style-type: none"> Output1 - Output5 	<ul style="list-style-type: none"> Shorting jumper removed: Resistance OFF
<ul style="list-style-type: none"> 20-30 VDC 	<ul style="list-style-type: none"> Shorting jumper inserted: Resistance ON

Electrical Data

Input Voltage	20-30 V DC
Current Consumption at 24V	36mA
Input current on each input	6.28mA at 24V
Relays K1 - K5 voltage/current ratings	125VAC/0.5A, 30VDC/2A

Mechanical Data

Temperature	-40° C to +70° C
Dimensions (H x W x D)	132 x 87 x 28 mm

LED manual

LED	PATTERN	STATE
STATUS LED (white)	LED ON	Fully operational
	LED Blinking (Very Fast)	Initializing
	LED Blinking 3Hz (Fast)	Pre-Operational
	LED Blinking 1Hz (Slow)	Stopped
ERROR LED (red)	LED OFF	No Error
	LED Blinking (Slow)	CAN Bus Warning
	LED ON	Bus OFF Error *
	LED Blinking (Very Fast)	CAN Bus Passive *

* In “Bus OFF” and “Passive” state, the device is entering the automatic baudrate detection mode.

CANopen device profile for Lift



Conformed with quality management systems standards

